Vision-aided Inertial Navigation Systems Software from Multiple Autonomous Robotic Systems Laboratory

Technology ID
20170397

Category
Engineering & Physical Sciences/Instrumentation, Sensors & Controls
Engineering & Physical Sciences/Robotics

The Vision-aided Inertial Navigation Systems (VINS) algorithm uses visual and inertial data for tracking in real time the 3D position and attitude of an IMU-camera pair. Please visit the Multiple Autonomous Robotic Systems laboratory website for more information.

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