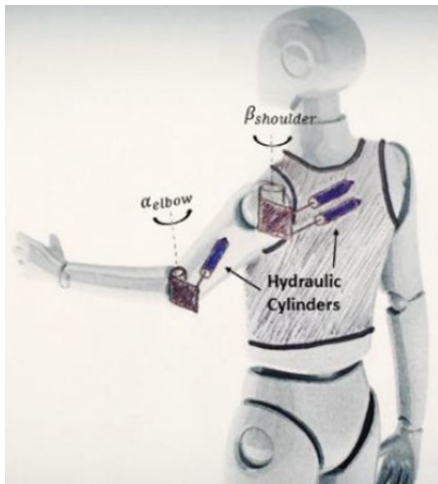




Long-stroke rolling diaphragm cylinder for passive hydraulic rehabilitation robot

Novel fabric-elastomer long-stroke rolling diaphragm (LSRD) cylinder displaying low friction and zero leakage for small and passive hydraulic systems.



IP Status: US Patent Issued # 11,300,116

Applications

- Wearable hydraulic rehabilitation robots
- Telepresence devices

Key Benefits & Differentiators

- **Higher stroke-bore ratio:** by using a new fabric-elastomer manufacturing method
- **Light-weight:** this novel LSRD is over 5 times lighter than commercially available ones

Technology Overview

Hydraulic cylinders are the most commonly used actuators for small, passive hydraulic systems such as passive human body controlled devices. One example is rehabilitation robots where the transmission extracts power from functioning muscle groups and delivers it to assist or guide stroke-affected muscle groups. In this system friction and leakage of the actuator are crucial, and typically rolling diaphragm cylinders perform best. However, rolling diaphragms currently available are limited to a stroke length being no greater than the bore of the cylinder. This restriction on the stroke length affects the work per cycle of the system and as a consequence decreases efficiency of the actuators.

To address this issue researchers at the University of Minnesota have developed a long-stroke rolling diaphragm (LSRD) cylinder that can be manufactured with any stroke length (i.e, it is not limited to the standard the 1:1 stroke-to-bore ratio) while also displaying low friction and no

Technology ID

20180407

Category

Engineering & Physical Sciences/Design Specifications
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leakage. Several tests have been conducted to evaluate the dynamic performance of this device including friction, stiffness, tracking impulse response, and step response. Results showed this new LSRD cylinder could operate at loads up to 700 kPa. In addition, a fatigue test of 1000 cycles showed a burst pressure of 350 psi could be reached. Thus, this novel device could enable actuators in small-scale hydraulic devices to achieve high force and volume efficiencies.

Phase of Development

TRL: 3-4

A method of manufacturing and a working prototype of a long-stroke rolling diaphragm (LSRD) cylinder have been developed. This newly developed rolling diaphragm cylinder has been incorporated into the upper-limb rehabilitation robot (eMobt) as an actuator- a project funded by the National Institutes of Health (NRI).

Desired Partnerships

This technology is now available for:

- License
- Sponsored research
- Co-development

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Researchers

- [William Durfee, PhD](#) Professor, Mechanical Engineering Department.

References

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